Math 254-1 Exam 2b Solutions

1. Carefully state the definition of "dependent", in the context of this course. Give 2 examples from \mathbb{R}^2 .

A set of vectors is dependent if there is a nondegenerate linear combination yielding the zero vector. Many examples are possible: $\{(1,2), (2,4)\}$ satisfies 2(1,2) - (2,4) = (0,0); $\{(1,2), (2,3), (3,4)\}$ has three elements while dim $\mathbb{R}^2 = 2$, hence must be dependent.

	$x_1 - 2x_2 + 2x_3$	=	1	
	$2x_1 - 3x_2 + 4x_3 + 5x_4$	=	8	
owing system:	$2x_2 + 16x_4$	=	18	
	$-2x_1 + 2x_2 - 4x_3 + 2x_4$	=	-2	
	$3x_1 - 6x_2 + 6x_3 + 6x_4$	=	9	

- The remaining problems all concern the following syst
- 2. Write the above system as a matrix equation.

This system, like all linear systems, can be written as Ax = b.

$A = \begin{bmatrix} 1 & -2 & 2 & 0 \\ 2 & -3 & 4 & 5 \\ 0 & 2 & 0 & 16 \\ -2 & 2 & -4 & 2 \\ 3 & -6 & 6 & 6 \end{bmatrix}$	$\left], x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}, b =$	$\begin{bmatrix} 1\\8\\18\\-2\\9\end{bmatrix}.$
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3. Write the above system as an augmented matrix. Put this in echelon form, justifying each step using elementary row operations. Using the echelon form, find all solutions to the system.

$$\begin{bmatrix} 1 & -2 & 2 & 0 & 1 \\ 2 & -3 & 4 & 5 & 8 \\ 0 & 2 & 0 & 16 & 18 \\ -2 & 2 & -4 & 2 & -2 \\ 3 & -6 & 6 & 6 & 9 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & 2 & 0 & 1 \\ 0 & 1 & 0 & 5 & 6 \\ 0 & 2 & 0 & 16 & 18 \\ 0 & -2 & 0 & 2 & 0 \\ 0 & 0 & 0 & 6 & 6 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & 2 & 0 & 1 \\ 0 & 1 & 0 & 5 & 6 \\ 0 & 0 & 0 & 12 & 12 \\ 0 & 0 & 0 & 6 & 6 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & 2 & 0 & 1 \\ 0 & 1 & 0 & 5 & 6 \\ 0 & 0 & 0 & 12 & 12 \\ 0 & 0 & 0 & 6 & 6 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & 2 & 0 & 1 \\ 0 & 1 & 0 & 5 & 6 \\ 0 & 0 & 0 & 6 & 6 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\{ -2R_1 + R_2 \rightarrow R_2, 2R_1 + R_4 \rightarrow R_4, -3R_1 + R_5 \rightarrow R_5 \},$$

$$\{ -2R_2 + R_3 \rightarrow R_3, 2R_2 + R_4 \rightarrow R_4 \}, \{ -2R_3 + R_4 \rightarrow R_4, -R_3 + R_5 \rightarrow R_5 \},$$

$$\{ 6x_4 = 6, \text{ hence } x_4 = 1. \ x_3 \text{ is free. } x_2 + 5x_4 = 6, \text{ hence } x_2 = 1. \ x_1 - 2x_2 + 2x_3 = 1, \text{ hence } x_1 = 3 - 2x_3. \text{ The general solution is } (3 - 2x_3, 1, x_3, 1).$$

4. Write the above system as an augmented matrix. Put this in row canonical form, justifying each step using elementary row operations. Using the row canonical form, find all solutions to the system.

5. Write the homogeneous system associated to the above system. Solve this homogeneous system. Then use the particular solution (1, 1, 1, 1) to give the general solution to the original system.

The homogeneous system is $Ax = 0 = (0, 0, 0, 0, 0)^T$. Its augmented matrix is identical to the one above, except that the rightmost column is all zeroes.

$\begin{bmatrix} -2 & 2 & -4 & 2 & 0 \end{bmatrix}$	$\begin{bmatrix} 1 & 0 & 2 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0$	(with the same operations as above)
The general solution to the	homogonooug	$x_{1} = x_{2} = 0$ $x_{2} = -2x_{2}$ is $(-2a)$

The general solution to the homogeneous system is $x_4 = x_2 = 0$, $x_1 = -2x_3$, i.e. (-2a, 0, a, 0). We add this to the specific solution (1, 1, 1, 1) to get the general solution (1 - 2a, 1, 1 + a, 1).